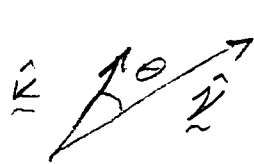


$$v_1 k_2 - v_2 k_1 \rightarrow -v_1 k_2 + v_2 k_1 = -(v_1 k_2 - v_2 k_1)$$

Thus, hemitropy + flip symmetry \Rightarrow

$$\Gamma(\dots, -\underline{e}_3 \cdot (\hat{\underline{v}} \times \hat{\underline{k}}), \dots) = \Gamma(\dots, \underline{e}_3 \cdot (\hat{\underline{v}} \times \hat{\underline{k}}), \dots),$$

which seems to imply that Γ should be a function of $(\underline{e}_3 \cdot \hat{\underline{v}} \times \hat{\underline{k}})^2$. However, note that (in the \underline{e}_1 - \underline{e}_2 plane):



$$(\hat{\underline{v}} \cdot \hat{\underline{k}})^2 = |\hat{\underline{v}}|^2 |\hat{\underline{k}}|^2 \cos^2 \theta$$

and

$$(\underline{e}_3 \cdot \hat{\underline{v}} \times \hat{\underline{k}})^2 = |\hat{\underline{v}}|^2 |\hat{\underline{k}}|^2 \sin^2 \theta$$

$$\begin{aligned} \Rightarrow (\underline{e}_3 \cdot (\hat{\underline{v}} \times \hat{\underline{k}}))^2 &= |\hat{\underline{v}}|^2 |\hat{\underline{k}}|^2 (1 - \cos^2 \theta) \\ &= |\hat{\underline{v}}|^2 |\hat{\underline{k}}|^2 - (\hat{\underline{v}} \cdot \hat{\underline{k}})^2, \end{aligned}$$

which is a combination of other invariants. Accordingly,

$$\boxed{\text{nem. (+ flip)} \Leftrightarrow \Gamma(\underline{v}, \underline{k}) = \overset{\sim}{\Gamma}(|\hat{\underline{v}}|^2, |\hat{\underline{k}}|^2, \hat{\underline{v}} \cdot \hat{\underline{k}}, v_3, k_3}$$

\uparrow homogeneous

Note: to quadratic order, we now have (**) p. 156 with $D=0$.

Isotropy (+ homogeneity = flip symmetry)

The symmetry group is now.

$$O_2(\omega) = \{ R(\theta), \bar{E} R(\theta) : 0 \leq \theta < 2\pi \},$$

i.e., the rod is hemitropic (flip invariant), and

$$\mathcal{I}(\bar{E} \bar{v}, -\bar{E} \bar{k}) = \mathcal{I}(\bar{v}, \bar{k}).$$

with $\bar{E} = -1$ (see (*) p. 153)

Now $\bar{E} \bar{v} = (v_1, -v_2, v_3)$, $-\bar{E} \bar{k} = (-k_1, k_2, -k_3)$.

$$\Rightarrow |\hat{v}|^2 \rightarrow |\hat{v}|^2, |\hat{k}|^2 \rightarrow |\hat{k}|^2, \hat{v} \cdot \hat{k} \rightarrow -v_1 k_1 - v_2 k_2 = -\hat{v} \cdot \hat{k}$$

and $k_3 \rightarrow -k_3$.

\therefore Isotropic (homogeneous = flip symmetric)

$$\Gamma(|\hat{v}|^2, |\hat{k}|^2, -\hat{v} \cdot \hat{k}, v_3, -k_3) = \tilde{\Gamma}(|\hat{v}|^2, |\hat{k}|^2, \hat{v} \cdot \hat{k}, v_3, k_3)$$

$$\mathcal{I}(\bar{v}, \bar{k}) = \sum_1 (|\hat{v}|^2, |\hat{k}|^2, k_3^2, (\hat{v} \cdot \hat{k})^2, (\hat{v} \cdot \hat{k}) k_3, v_3).$$

in some other form

Observe that no coupling of the form $k_3(v_3 - 1)$ is ^{now} allowed - only via $k_3^2(v_3 - 1)$ (say).

In other words "handedness" is now absent.

This is more transparent if we compare the quadratic approximation of (*) above, viz.,

$$(*) \quad \mathcal{I}(\bar{v}, \bar{k}) = \frac{1}{2} \{ A |\hat{v}|^2 + B |\hat{k}|^2 + E (v_3 - 1)^2 + F k_3^2 \}$$

with (***) p. 156 ($D=0$).

claim: $f(x, y) = f(-x, -y) \Leftrightarrow f(x, y) = g(x^2, y^2, xy)$
 Pf. Same as p. 157 or 158 (try it!).

Constraints

Like incompressibility in the 3-d theory, there are some common constraints that are often (typically) employed in rod problems:

1) Inextensibility:

Impose the constraint $\underline{r}' = \nu_3 \underline{d}_3$ ($\nu_1 = \nu_2 = 0$)
In this case,

$$\underline{r} = \nu_1 \underline{d}_1 + \nu_2 \underline{d}_2 + \nu_3 \underline{d}_3,$$

where ν_1, ν_2 primary unknowns (Lagrange multipliers), and the free energy function reduces to

$$W = \mathcal{I}(\nu_3, \kappa_1, \kappa_2, \kappa_3), \text{ where}$$

$$\nu_3 = \frac{\partial \mathcal{I}}{\partial \nu_3}, \quad \mu_i = \frac{\partial \mathcal{I}}{\partial \kappa_i}, \quad i = 1, 2, 3$$

Note: ν_1 & ν_2 are not "elastically" determined by the constitutive law.

2) Inextensibility:

$$\text{Impose } \underline{r}' = \nu_1 \underline{d}_1 + \underline{d}_3 \quad (\nu_3 = 1)$$

In this case, $W = \mathcal{I}(\nu_1, \nu_2, \kappa_1, \kappa_2, \kappa_3)$ and

$$\underline{n} = \frac{\partial \mathcal{F}}{\partial \underline{v}_\alpha} \underline{d}_\alpha + n_3 \underline{d}_3,$$

where n_3 is a primary unknown (Lagrange multiplier).

3) Inextensible, unstretchable

This is by far the most popular case (typically with linear elasticities - Love, Landau & Lifschitz, etc):

$$\text{Impose } \underline{r}' = \underline{d}_3 \quad (v_1 = v_2 = 0, v_3 = 1).$$

Then $\mathcal{W} = \mathcal{F}(\underline{K})$, and \underline{n} itself is a vector-valued Lagrange multiplier.

Exercise (22) The internal potential energy functional for an unstretchable, inextensible rod is given by (cf. p. 143)

$$\mathcal{V}[\underline{r}, \underline{R}] = \int_0^L \mathcal{F}(\underline{R}^T \underline{K}) ds,$$

where $\mathcal{F}(\underline{K}) = \mathcal{F}(\underline{R}^T \underline{K})$ is the free energy. Use the Lagrange-multiplier method to enforce the constraint $\underline{r}' - \underline{d}_3 = \underline{r}' - \underline{R} \underline{e}_3 = \underline{0}$, viz., find the stationary conditions for the functional

$$\tilde{V}[\underline{r}, \underline{R}, \underline{n}] = \int_0^L [\Psi(\underline{R}^T \underline{k}) + \lambda \cdot (\underline{r}' - \underline{R} \underline{e}_3)] ds$$

Lagrange mult.

As on pp. 147, integrate by parts and compare with pp. 126 to deduce that $\underline{\lambda} \equiv \underline{n}$.

Now let's compare the quadratic approximations for homogeneous hemitropy (+ "flip") (**) p. 156 (w/ $D=0$):

$$\mathcal{W}(\underline{v}, \underline{k}) = \frac{1}{2} \left\{ A \underline{\hat{v}} \cdot \underline{\hat{v}} + B \underline{\hat{k}} \cdot \underline{\hat{k}} + 2C \underline{\hat{v}} \cdot \underline{\hat{k}} + E(\nu_3 - 1) + F k_3^2 + 2G(\nu_3 - 1)k_3 \right\}$$

w/ homogeneous isotropy (+ "flip") (*) p. 161:

$$\mathcal{W}(\underline{v}, \underline{k}) = \frac{1}{2} \left\{ A \underline{\hat{v}} \cdot \underline{\hat{v}} + B \underline{\hat{k}} \cdot \underline{\hat{k}} + E(\nu_3 - 1)^2 + F k_3^2 \right\}$$

Observe in the classical Kirchhoff case quadratic + inextensible unsharable, the two energies are the same!

Strong Ellipticity

Next we investigate the ramifications of strong ellipticity (SE) p. 114 within the context of our rod theory (as a constrained 3-d body):

Claim: If we view hyperelastic rod theory as coming from a constrained 3-d hyperelastic theory (cf. pp. 123, 135, 142-143), then

$$(SE) \Rightarrow D^2 \Pi(\bar{v}, \bar{z}) = \begin{pmatrix} \frac{\partial^2 \Pi}{\partial \bar{v}^2} & \frac{\partial^2 \Pi}{\partial \bar{v} \partial \bar{z}} \\ \frac{\partial^2 \Pi}{\partial \bar{z} \partial \bar{v}} & \frac{\partial^2 \Pi}{\partial \bar{z}^2} \end{pmatrix}$$

is positive definite.

Pf. To see this, return to the calculations on p. ¹⁴¹142: E.g.)

$$\frac{\partial \Pi}{\partial v_i} = \int_{\Omega} \frac{\partial W}{\partial F} \left(R \left[\underline{e}_\alpha \otimes \underline{e}_\alpha + (v_i \underline{e}_i + I_\alpha \kappa_i \underline{e}_i \times \underline{e}_\alpha) \otimes \underline{e}_3 \right] \cdot \left(\underline{e}_i \otimes \underline{e}_3 \right) dA \right)$$

$$\therefore \frac{\partial^2 \Pi}{\partial v_i \partial v_j} = \int_{\Omega} \underline{d}_i \otimes \underline{e}_3 \cdot \frac{\partial^2 W}{\partial F^2}(\underline{F}_i) \left[\underline{d}_j \otimes \underline{e}_3 \right] dA$$