

The other "strains" are less transparent:

$K_{\alpha\beta} = \underline{a}_\alpha \cdot \underline{d}_{,\beta}$ is related to the 2nd

fundamental form of the surface $\underline{r}(\underline{\sigma})$. If $\underline{d} \equiv \underline{n}$ unit normal, then " $K_{\alpha\beta}$ " are precisely the components of the 2nd fund. form. Finally $\delta_\alpha = \underline{d} \cdot \underline{d}_{,\alpha}$, $\alpha = 1, 2$, are sometimes called the "couple stresses".

"Kirchhoff-Love" theory

Let's now focus our attention on the so-called special Cosserat theory, viz., we make the assumption

$$(*) \quad \underline{d} \cdot \underline{d} \equiv 1 \quad (\text{unit director})$$

From the top of p. 217, we conclude that

$$\underline{d} \cdot \underline{d} \equiv 1,$$

similarly, we have

$$(\underline{d} \cdot \underline{d})_{,\alpha} = 2 \underline{d} \cdot \underline{d}_{,\alpha} \equiv 0$$

\Rightarrow

$$\delta_\alpha = 0, \quad \alpha = 1, 2.$$

Hence the remaining strain measures are

$$\underline{c} = a_{\alpha\beta} \underline{e}_\alpha \otimes \underline{e}_\beta, \quad \underline{k} = K_{\alpha\beta} \underline{e}_\alpha \otimes \underline{e}_\beta \quad \text{and} \quad \underline{d} = \delta_\alpha \underline{e}_\alpha$$

Thus the free-energy density reduces to

$$\underline{\Phi} = \mathcal{F}(\underline{e}, \underline{v}, \underline{\xi})$$

Now in this constrained theory (*) p. 218) it is illuminating to observe that we essentially have 5 unknown fields - $\underline{r}, \underline{d}$ subject to $|\underline{d}| = 1$ - and then to also consider $\underline{d} \times$ (*) p. 207:

$$\underline{d} \times (\underline{M}_{\alpha, \alpha} - \underline{\sigma} + \underline{\hat{L}}) = \mathcal{J}_0 \underline{d} \times \underline{d}_{tt}$$

$$\Rightarrow (\underline{d} \times \underline{M}_{\alpha, \alpha})_{, \alpha} - \underline{d}_{, \alpha} \times \underline{M}_{\alpha} - \underline{d} \times \underline{\sigma} + \underline{d} \times \underline{\hat{L}} = \mathcal{J}_0 \underline{d} \times \underline{d}_{tt}$$

p. 204

$$\Rightarrow \underline{M}_{\alpha, \alpha} - (\underline{d}_{, \alpha} \times \underline{M}_{\alpha} + \underline{d} \times \underline{\sigma}) + \underline{\hat{g}} = \mathcal{J}_0 \underline{d} \times \underline{d}_{tt}$$

$\underline{\nabla} \cdot \underline{M}$

But by virtue of the Thm. on p. 217, we have (hyperelasticity)

$$-(\underline{d}_{, \alpha} \times \underline{M}_{\alpha} + \underline{d} \times \underline{\sigma}) = \underline{r}_{, \alpha} \times \underline{N}_{\alpha}$$

$$\Rightarrow \underline{M}_{\alpha, \alpha} + \underline{r}_{, \alpha} \times \underline{N}_{\alpha} + \underline{\hat{g}} = \mathcal{J}_0 \underline{d} \times \underline{d}_{tt}$$

Of course this is simply (AMB) again (cf. (*) p. 203)

However, what we learn here is that

$$\underline{d} \cdot (\text{AMB}) = 0, \text{ i.e., } (\text{AMB}) \text{ essentially delivers}$$

2 scalar equations. So $(\text{LMB}) + (\text{AMB})$ gives essentially 5 equations, which are enough (with constitutive laws) to determine the 5 unknowns $\underline{k}, \underline{d}$ (subject to $|\underline{d}| \equiv 1$). In the absence of the constraint, we need $(\text{LMB}) + (\text{director-MB})$ (p. 207), the latter of which has 3 components.

Henceforth, we concentrate solely on Kirchhoff plates:

We enforce not only $(*) |\underline{d}| \equiv 1$, but also the two constraints

$$(**) \underline{a}_\alpha \cdot \underline{d} \equiv 0, \quad \alpha = 1, 2.$$

Together $(*)$ & $(**)$ $\Rightarrow \underline{d}$ is a unit normal vector field, i.e.,

$$\underline{d} = \frac{\underline{a}_1 \times \underline{a}_2}{|\underline{a}_1 \times \underline{a}_2|} \equiv \underline{n}$$

Exercise (27) Show that

$$J \equiv |\underline{a}_1 \times \underline{a}_2| = \sqrt{\det \underline{c}} \quad \text{local area change.}$$

(p. 215)

Hint $\underline{\underline{F}}_m = \underline{\underline{a}}_\alpha \otimes \underline{\underline{e}}_\alpha + \underline{\underline{n}} \otimes \underline{\underline{e}}_3$

compute $\det \underline{\underline{C}}_m$.

Of course ~~(*)~~ p. 220 shows that the shear strains γ_α , $\alpha = 1, 2$, are zero. But also

(p. 217)

$$K_{\alpha\beta} = \underline{\underline{a}}_\alpha \cdot \underline{\underline{d}}_{|\beta} = \underline{\underline{a}}_\alpha \cdot \underline{\underline{n}}_{|\beta} = -b_{\alpha\beta}$$

(components
of the 2nd
fund. form
in diff. geom)

Observe $\underline{\underline{a}}_\alpha \cdot \underline{\underline{n}} = 0$

$$\Rightarrow \underline{\underline{a}}_{\alpha|\beta} \cdot \underline{\underline{n}} + \underline{\underline{a}}_\alpha \cdot \underline{\underline{n}}_{|\beta} = 0$$

or $K_{\alpha\beta} = -\underline{\underline{a}}_{\alpha|\beta} \cdot \underline{\underline{n}}$

$$= -\underline{\underline{a}}_{\beta|\alpha} \cdot \underline{\underline{n}} = K_{\beta\alpha}$$

symmetric!

i.e., $\underline{\underline{K}} = K_{\alpha\beta} \underline{\underline{e}}_\alpha \otimes \underline{\underline{e}}_\beta$,

where $\underline{\underline{K}} = \nabla_{\underline{\underline{r}}}^T \nabla \underline{\underline{d}}$ (p. 217), then

$$\underline{\underline{K}}^T = \underline{\underline{K}}.$$

Next let's proceed with the structure of the field equations in the presence of ~~(*)~~ & ~~(**)~~ p. 220 via Lagrange multipliers:

From p. 210, we have

$$\mathcal{V} = \int_{\Omega} \left[\bar{\mathbb{E}}(\underline{r}_\alpha, \underline{d}, \underline{d}_\alpha) - \frac{\mu}{2} (\underline{d} \cdot \underline{d} - 1) - q_\alpha \underline{r}_\alpha \cdot \underline{d} \right] dA + \dots \quad (*)$$

Then

$$\begin{aligned} \delta \mathcal{V} &= \int_{\Omega} \left(\frac{\delta \bar{\mathbb{E}}}{\delta \underline{r}_\alpha} - q_\alpha \underline{d} \right) \cdot \underline{\eta}_{1, \alpha} \\ &+ \left[\frac{\delta \bar{\mathbb{E}}}{\delta \underline{d}} - \left(\mu \underline{d} + q_\alpha \underline{r}_\alpha \right) \right] \cdot \underline{\varepsilon} \\ &+ \dots = 0 \quad \forall \text{ adm } \underline{\eta}_1, \underline{\varepsilon} \end{aligned}$$

The first term above shows that $\underline{N}_\alpha, \alpha = 1, 2$, has a constitutively indeterminate component along \underline{d} :

$$(*) \quad \underline{N}_\alpha = \bar{\underline{N}}_\alpha + q_\alpha \underline{d}$$

$$\bar{\underline{N}}_\alpha = \frac{\delta \bar{\mathbb{E}}}{\delta \underline{r}_\alpha}, \quad \bar{\underline{N}}_\alpha \cdot \underline{d} \equiv 0, \quad \alpha = 1, 2.$$

The second expression shows that

$$\underline{\sigma} = q_\alpha \underline{a}_\alpha + \mu \underline{d} \quad \text{is constitutively indeterminate} \quad \checkmark$$

which, as shown on p. 219, falls out of (AMB).

In-Plane Material Symmetry

Define the symmetry operations

$$\underline{\underline{R}}(\theta) \equiv \cos\theta (\underline{e}_1 \otimes \underline{e}_1 + \underline{e}_2 \otimes \underline{e}_2) + \sin\theta (\underline{e}_1 \otimes \underline{e}_2 - \underline{e}_2 \otimes \underline{e}_1),$$

$$\underline{\underline{I}} \equiv \underline{e}_1 \otimes \underline{e}_1 - \underline{e}_2 \otimes \underline{e}_2,$$

and the orthogonal group on \mathbb{E}^2 :

$$O(2) = \{ \underline{\underline{R}}(\theta), \underline{\underline{I}} \underline{\underline{R}}(\theta) : 0 \leq \theta < 2\pi \}.$$

We take the same approach as before to motivate our definition via two "armchair" experiments:

- ① Apply a deformation such that the values such that the strains at $\underline{s} \in \Omega$ are \underline{C} and \underline{K} - say coming from

$$\underline{\underline{F}}^D = \underline{a}_\alpha \otimes \underline{e}_\alpha + \underline{d} \otimes \underline{e}_3 + \mathbb{I}_3 \underline{d}_\alpha \otimes \underline{e}_\alpha.$$

$$= \underline{\underline{F}} + \underline{d} \otimes \underline{e}_3 + \mathbb{I}_3 \underline{\underline{G}}, \text{ where}$$

$$\underline{C} = \underline{\underline{F}}^T \underline{\underline{F}}, \quad \underline{K} = \underline{\underline{F}}^T \underline{\underline{G}}.$$

We then "measure" $\mathcal{I}(\underline{C}, \underline{K})$.

② First rotate or reflect Ω according to $\underline{Q} \in O(2)$, and then perform \underline{f}_c^D on the transformed body $\underline{Q}(\Omega)$:

$$\begin{aligned}\underline{F}_c^{\textcircled{2}} &= \underline{a}_\alpha \otimes (\underline{Q} \underline{e}_\alpha) + \underline{d} \otimes \underline{e}_3 + \mathbb{I}_3 \underline{d}_{,\alpha} \otimes (\underline{Q} \underline{e}_\alpha) \\ &= \underline{F} \underline{Q}^T + \underline{d} \otimes \underline{e}_3 + \mathbb{I}_3 \underline{G} \underline{Q}^T,\end{aligned}$$

i.e., $\underline{F} \rightarrow \underline{F} \underline{Q}^T$, $\underline{G} \rightarrow \underline{G} \underline{Q}^T$, and thus,

$$\underline{c} \rightarrow (\underline{F} \underline{Q}^T)^T \underline{F} \underline{Q}^T = \underline{Q} \underline{c} \underline{Q}^T$$

$$\underline{K} \rightarrow (\underline{F} \underline{Q}^T)^T \underline{F} \underline{Q}^T = \underline{Q} \underline{K} \underline{Q}^T.$$

Again, we "measure" $\mathbb{I}(\underline{Q} \underline{c} \underline{Q}^T, \underline{Q} \underline{K} \underline{Q}^T)$.

Definition: $\underline{Q} \in O(2)$ is an in-plane material symmetry (of Ω at \underline{s}) if

$$(*) \quad \mathbb{I}(\underline{Q} \underline{c} \underline{Q}^T, \underline{Q} \underline{K} \underline{Q}^T) = \mathbb{I}(\underline{c}, \underline{K})$$

for all $\underline{c}, \underline{K} \in \text{Sym}(\mathbb{E}^2)$
(actually $\underline{c} \in \text{Sym}^+(\mathbb{E}^2)$).

If (*) holds for all $\underline{Q} \in O(2)$, we say that Ω is in-plane isotropic.