

$\therefore$  In-plane isotropy + mid-plane symmetry:

$$(*) \quad \mathcal{I}(\mathcal{I}_1, \mathcal{I}_2, -\mathcal{I}_3, \mathcal{I}_4, -\mathcal{I}_5) = \mathcal{I}(\mathcal{I}_1, \mathcal{I}_2, \dots, \mathcal{I}_5).$$

Thm  $(*) \Leftrightarrow$

$$\underline{\Phi} = \mathcal{I} = \mathcal{I}(\mathcal{I}_1, \mathcal{I}_2, \mathcal{I}_3^2, \mathcal{I}_4, \mathcal{I}_5^2, \mathcal{I}_3 \mathcal{I}_5).$$

PF (see p. 161).

### Lecture 29

## Stress and Stress-Couple Resultants (Kirchhoff Theory)

Returning to p. 212, in the context of the Kirchhoff theory ( $\underline{\sigma}$  is constitutively indeterminate p. 222 - bottom), we now write the stored-energy function as

$$\underline{\Phi} = \Psi(\underline{F}, \underline{G})$$

$$= \mathcal{I}(\underline{C}, \underline{K}) - \text{using (M0) (p. 215)}.$$

Now from p. 213, we have

$$\underline{N} = \frac{\partial \Psi}{\partial \underline{F}} \quad \text{and} \quad \underline{\mu} = \frac{\partial \Psi}{\partial \underline{G}}$$

Our goal here is to work out what these

look like in terms of  $\mathcal{I}(\underline{c}, \underline{K})$ . Consider

$$\left. \frac{d}{d\alpha} \mathcal{I}(\underline{F} + \alpha \underline{A}, \underline{G}) \right|_{\alpha=0} \quad \underline{A} \in L(\mathbb{E}^2, \mathbb{E}^3)$$

$$= \left. \frac{d}{d\alpha} \mathcal{I}(\left(\underline{F}^T + \alpha \underline{A}^T\right)\left(\underline{F} + \alpha \underline{A}\right), \left(\underline{F}^T + \alpha \underline{A}^T\right)\underline{G}) \right|_{\alpha=0}$$

$$\frac{\partial \mathcal{I}}{\partial \underline{F}} \cdot \underline{A} = \frac{\partial \mathcal{I}}{\partial \underline{c}} \cdot \left(\underline{F}^T \underline{A} + \underline{A}^T \underline{F}\right)$$

$$+ \frac{\partial \mathcal{I}}{\partial \underline{K}} \cdot \underline{A}^T \underline{G}$$

Call  $\underline{N} \equiv \frac{\partial \mathcal{I}}{\partial \underline{c}}$  and  $\underline{M} \equiv \frac{\partial \mathcal{I}}{\partial \underline{K}}$

Then  $\underline{N} \cdot \left(\underline{F}^T \underline{A} + \underline{A}^T \underline{F}\right)$

$$= \underline{N}_{\alpha\beta} \left[ \left(\underline{F}^T\right)_{\alpha i} A_{i\beta} + \left(\underline{A}^T\right)_{\alpha i} F_{i\beta} \right]$$

$$= \underline{N}_{\alpha\beta} \left( F_{i\alpha} A_{i\beta} + A_{i\alpha} F_{i\beta} \right)$$

$$= F_{i\alpha} \underline{N}_{\alpha\beta} A_{i\beta} + F_{i\beta} \underline{N}_{\alpha\beta} A_{i\alpha}$$

$$= \underline{F} \underline{N} \cdot \underline{A} + \underline{F} \underline{N}^T \cdot \underline{A}$$

$$= 2 \underline{F} \underline{N} \cdot \underline{A} \quad \left( \underline{N}^T = \underline{N} \text{ why?} \right)$$

$$\therefore \underline{N} \cdot \underline{A} = \frac{\partial \mathcal{F}}{\partial \underline{F}} \cdot \underline{A}$$

$$= \left( \underline{z} \underline{F} \frac{\partial \mathcal{N}}{\partial \underline{c}} + \underline{G} \frac{\partial \mathcal{N}}{\partial \underline{K}} \right) \cdot \underline{A} \quad \forall \underline{A}$$

$$(*) \Rightarrow \boxed{\underline{N} = \underline{z} \underline{F} \frac{\partial \mathcal{N}}{\partial \underline{c}} + \underline{G} \frac{\partial \mathcal{N}}{\partial \underline{K}}}$$

Observe  $\frac{\partial \mathcal{N}}{\partial \underline{c}} \underline{e}_\alpha, \frac{\partial \mathcal{N}}{\partial \underline{K}} \underline{e}_\alpha \in \mathbb{F}^2 = \text{span}\{\underline{e}_1, \underline{e}_2\}$

$$\begin{aligned} \therefore \underline{N} \underline{e}_\alpha &= \underline{z} \underline{F} (\nu_\gamma \underline{e}_\gamma) + \underline{G} (\mu_\gamma \underline{e}_\gamma) \\ &= \underline{z} (\underline{a}_\beta \otimes \underline{e}_\beta) (\nu_\gamma \underline{e}_\gamma) + (\underline{n}_\beta \otimes \underline{e}_\beta) (\mu_\gamma \underline{e}_\gamma) \\ &= \underline{z} \nu_\beta \underline{a}_\beta + \underline{\mu}_\beta \underline{n}_\beta \end{aligned}$$

$$\text{and } \underline{n} \cdot \underline{N} \underline{e}_\alpha = \cancel{\underline{z} \nu_\beta \underline{a}_\beta \cdot \underline{n}} + \cancel{\underline{\mu}_\beta \underline{n}_\beta \cdot \underline{n}} \quad (\underline{n} \cdot \underline{n} \equiv 1)$$

$$\Rightarrow \underline{N}_\alpha = \boxed{\underline{z} \underline{F} \frac{\partial \mathcal{N}}{\partial \underline{c}} + \underline{G} \frac{\partial \mathcal{N}}{\partial \underline{K}}}$$

(\*) p. 222)

$$\downarrow \underline{N}_\alpha = \underline{N}_\alpha + q_\alpha \underline{n}$$

similarly,

$$\frac{d}{d\alpha} \Psi(\underline{F}, \underline{G} + \alpha \underline{B}) \Big|_{\alpha=0} = \frac{d}{d\alpha} \mathcal{M}(\underline{e}, \underline{F}(\underline{G} + \alpha \underline{B})) \Big|_{\alpha=0}$$

$$\Rightarrow \frac{\partial \Psi}{\partial \underline{G}} \cdot \underline{B} = \frac{\partial \mathcal{M}}{\partial \underline{K}} \cdot \underline{F}^T \underline{B} = \underline{F} \frac{\partial \mathcal{M}}{\partial \underline{K}} \cdot \underline{B} \quad \forall \underline{B} \in L(\underline{E}^2, \underline{E}^3)$$

$$\Rightarrow \underline{\underline{M}} = \underline{F} \frac{\partial \mathcal{M}}{\partial \underline{K}}$$

$$\underline{\underline{M}}_\alpha = \underline{F} \frac{\partial \mathcal{M}}{\partial \underline{K}} \underline{e}_\alpha$$

$$\underline{\underline{M}}_\alpha = \underline{\underline{M}} \times \underline{F} \frac{\partial \mathcal{M}}{\partial \underline{K}} \underline{e}_\alpha$$

### Orientation Preservation

Here we pause to note the "ghost" of local injectivity from 3-d nonl. elasticity —  $\det \underline{F} > 0$ . As with rods, we look at  $\underline{F}_c|_{\mathbb{I}_3=0} = \nabla_{\underline{\tilde{r}}} + d \otimes \underline{e}_3$

$$\det \underline{F}_c|_{\mathbb{I}_3=0} = \det \begin{bmatrix} (\underline{r}_1)_1, (\underline{r}_2)_1, (d)_1 \\ (\underline{r}_1)_2, (\underline{r}_2)_2, (d)_2 \\ (\underline{r}_1)_3, (\underline{r}_2)_3, (d)_3 \end{bmatrix}$$

$$= \underline{(\underline{r}_1 \times \underline{r}_2)} \cdot \underline{d} > 0$$

local injectivity

## Strong Ellipticity

In the context of the Kirchhoff theory, we return to (SE) pp. 114 and 116 in the context of p. 212:

$$\Psi(\underline{F}, \underline{G}) = \int_{-h/2}^{h/2} W(\underline{F} + \underline{I}_3 \underline{G} + \underline{n} \otimes \underline{e}_3) d\underline{X}_3$$

Consider a "rank-one excursion" in  $\underline{F} \in L(\mathbb{E}^3, \mathbb{E}^3)$ :

$$\underline{F} + \alpha \underline{a} \otimes \underline{b} \quad \text{where } \underline{a} \in \mathbb{E}^3, \underline{b} \in \mathbb{E}^2 \\ \underline{a} \neq \underline{0} \quad \underline{b} \neq \underline{0}$$

$$\text{Then } \left. \frac{d^2}{d\alpha^2} \Psi(\underline{F} + \alpha \underline{a} \otimes \underline{b}, \underline{G}) \right|_{\alpha=0}$$

$$= \underline{a} \otimes \underline{b} \cdot \frac{\partial^2 \Psi}{\partial \underline{F}^2}(\underline{F}, \underline{G})[\underline{a} \otimes \underline{b}]$$

$$= \int_{-h/2}^{h/2} \underline{a} \otimes \underline{b} \cdot \frac{\partial^2 W}{\partial \underline{F}^2}(\underline{F}_c) [\underline{a} \otimes \underline{b}] d\underline{X}_3 > 0 \quad \begin{array}{l} \text{3-d} \\ \text{(SE)} \end{array}$$

$$\Rightarrow \boxed{(\ast) \quad \underline{a} \otimes \underline{b} \cdot \frac{\partial^2 \Psi}{\partial \underline{F}^2}(\underline{F}, \underline{G})[\underline{a} \otimes \underline{b}] > 0, \quad \forall \underline{a} \in \mathbb{E}^3, \underline{b} \in \mathbb{E}^2, \underline{a} \neq \underline{0}, \underline{b} \neq \underline{0}}$$

Observe that  $\frac{\partial^2 \Psi}{\partial \underline{F}^2}(\underline{F}, \underline{G}) \in L(L(\mathbb{E}^3, \mathbb{E}^3))$ , i.e.,

$$\underline{e}_i \otimes \underline{e}_\alpha \cdot \frac{\partial^2 \Psi}{\partial \underline{F}^2}(\underline{F}, \underline{G})[\underline{e}_j \otimes \underline{e}_\beta] = \frac{\partial^2 \Psi}{\partial F_{i\alpha} \partial F_{j\beta}}(\underline{F}, \underline{G}).$$

Next we consider a rank-one excursion  
in  $\underline{G} \in L(\mathbb{E}^2, \mathbb{E}^3)$ :

$$\Psi(\underline{F}, \underline{G} + \alpha \underline{a} \otimes \underline{b}) = \int_{-h/2}^{h/2} W(\underline{F} + \mathbb{I}_3(\underline{G} + \alpha \underline{a} \otimes \underline{b}) + \alpha \otimes \underline{e}_3) d\underline{x}_3$$

which is also an " $\mathbb{I}_3 \underline{a} \otimes \underline{b}$ " excursion in  $\underline{F}$ ". In any case

$$\left. \frac{d^2}{d\alpha^2} \Psi(\underline{F}, \underline{G} + \alpha \underline{a} \otimes \underline{b}) \right|_{\alpha=0}$$

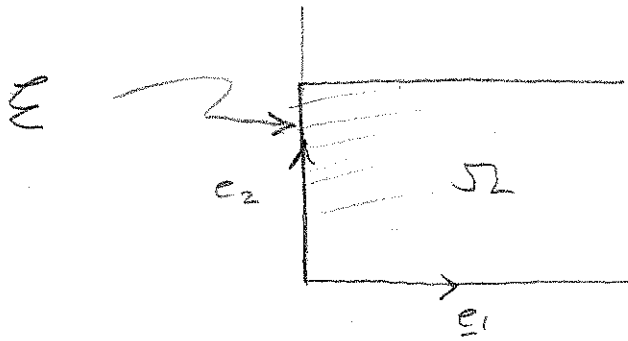
$$= \underline{a} \otimes \underline{b} \cdot \frac{d^2 \Psi}{d\underline{G}^2}(\underline{F}, \underline{G})[\underline{a} \otimes \underline{b}]$$

$$= \int_{-h/2}^{h/2} \mathbb{I}_3^2 \underline{a} \otimes \underline{b} \cdot \frac{d^2 W(\underline{F})}{d\underline{F}^2}(\underline{c})[\underline{a} \otimes \underline{b}] d\underline{x}_3 > 0 \quad (\text{SE})$$

$$(*) \Rightarrow \boxed{\underline{a} \otimes \underline{b} \cdot \frac{d^2 \Psi}{d\underline{G}^2}(\underline{F}, \underline{G})[\underline{a} \otimes \underline{b}] > 0 \quad \forall \underline{a} \in \mathbb{E}^3, \underline{b} \in \mathbb{E}^2, \underline{a} \neq \underline{0}, \underline{b} \neq \underline{0}.}$$

### Boundary Conditions

For simplicity, let's consider  
a straight edge, e.g.,  $\mathcal{E} = \{ \mathbb{I}_2 \underline{e}_2 : \mathbb{I}_2 \in (0, l) \}$



$$\textcircled{1} \text{ Clamped: } \left. \begin{array}{l} \underline{r}(0, x_2) \equiv x_2 \underline{e}_2 \\ \underline{s}_1(0, x_2) = \underline{e}_1 \Rightarrow \underline{n}(0, x_2) \equiv \underline{e}_3 \end{array} \right\} x_2 \in (0, l) \quad \leftarrow \Rightarrow \underline{r}_{12}(0, x_2) \equiv \underline{e}_2$$

$$\textcircled{2} \text{ Hinged: } (*) \left\{ \underline{r}(0, x_2) \equiv x_2 \underline{e}_2 \quad x_2 \in (0, l) \right\}$$

For the remaining b.c., we resort to a variational argument to obtain the natural boundary condition:

For admissibility we require  $\underline{n}(0, x_2) \equiv \underline{0}, x_2 \in (0, l)$ . From pp. 211-212, the term of interest to us is (since  $\underline{M}_\alpha = \underline{d} \times \underline{M}_\alpha$ )

$$(*) \quad \delta \tilde{V} = \int_{\Omega} \left[ \dots + \frac{\delta \Phi}{\delta d_\alpha} \cdot \underline{\varepsilon}_{1,\alpha} + \dots \right] dA = 0 \quad \forall \text{ ad } \underline{n}, \underline{\varepsilon}$$

Remark: the term involving  $\frac{\delta \Phi}{\delta d}$  is not of interest to us - it "falls out" of our formulation - see p. 219.

Let's examine (\*) p. 234 in detail:

$$\int_{\Omega} \frac{\partial \Phi}{\partial d_{\tilde{r}, \alpha}} \cdot \tilde{r}_{\tilde{r}, \alpha} dA = \int_{\Omega} \left( \tilde{M}_1 \cdot \frac{\partial \tilde{z}}{\partial X_1} + \tilde{M}_2 \cdot \frac{\partial \tilde{z}}{\partial X_2} \right) dA$$

Along edge  $\mathcal{E}$ , it is the first term above that contributes to the boundary condition:

$$\int_0^L \int_0^L \tilde{M}_1 \cdot \frac{\partial \tilde{z}}{\partial X_1} dX_1 dX_2$$

integrate by parts

$$U = \tilde{M}_1 \quad dV = \frac{\partial \tilde{z}}{\partial X_1} dX_1$$

$$dU = \frac{\partial \tilde{M}_1}{\partial X_1} dX_1 \quad V = \tilde{z}$$

$$= \int_0^L \left[ \tilde{M}_1 \cdot \tilde{z} \Big|_{X_1=0}^{X_1=L} - \int_0^L \frac{\partial \tilde{M}_1}{\partial X_1} \cdot \tilde{z} dX_1 \right] dX_2$$

Lecture 30

We want to examine the term at  $X_1 = 0$ :

$$(*) \int_0^L \tilde{M}_1(0, X_2) \cdot \tilde{z}(0, X_2) dX_2 = 0 \quad \forall \text{ adm. variations } \tilde{z}$$

But we need to be careful here about admissibility. Returning to (\*) and (\*\*) p. 220, we need:

$$\frac{d}{d\varepsilon} \left[ (\underline{n} + \varepsilon \underline{\tilde{z}}) \cdot (\underline{n} + \varepsilon \underline{\tilde{z}}) = 1 \right] \Big|_{\varepsilon=0}$$

$$\Rightarrow \underline{n} \cdot \underline{\tilde{z}} = 0$$